MITSUBISHI ELECTRIC

General-Purpose AC Servo

MITSUBISHI ELECTRIC SERVO SYSTEM
MELSERVO

Functional safety unit
Model
MR-D30
Installation Guide

K

Country/Region	Sales office	Tel
USA	Mitsubishi Electric Automation, Inc. 500 Corporate Woods Parkway, Vernon Hills, IL 60061, U.S.A.	Tel : +1-847-478-2100
Germany	Mitsubishi Electric Europe B.V. German Branch Mitsubishi-Electric-Platz 1, 40882 Ratingen, Germany	Tel : +49-2102-486-0
China	Mitsubishi Electric Automation (China) Ltd. Mitsubishi Electric Automation Center, No.1386 Hongqiao Road, Shanghai, China	Tel : +86-21-2322-3030
Korea	Mitsubishi Electric Automation Korea Co., Ltd. 7F to 9F, Gangseo Hangang Xi-tower A, 401, Yangcheon-ro, Gangseo-Gu, Seoul, Korea	Tel : +82-2-6103-9474
Japan	Mitsubishi Electric Corporation Tokyo Building, 2-7-3, Marunouchi, Chiyoda-ku, Tokyo 100-8310, Japan	Tel : +81-3-3218-2111

MITSUBISHI ELECTRIC CORPORATION

HEAD OFFICE: TOKYO BLDG., 2-7-3, MARUNOUCHI, CHIYODA-KU, TOKYO 100-8310, JAPAN

Specifications are subject to change without notice.
Compliance with the indicated global standards and regulations is current as of the release date of this installation guide.
The original instructions for Europe are in English.

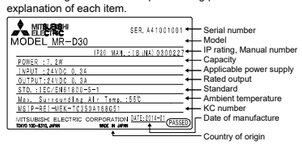
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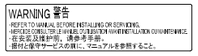
Contents of the package

Contents	Quantity
MR-D30 functional safety unit	1
MR-D30 Installation Guide (this guide)	1

Rating plate
The following shows an example of rating plate for explanation of each item.



Warning plate
An example of warning plate is shown below.



Regulation/legislation marking
An example of regulation/legislation marking is shown below.



1. About the manuals

To use the MR-D30 safely, read "MR-D30 Instruction Manual" carefully.

1.1 MELSERVO-J4 relevant manuals

This installation guide explains how to mount MR-J4 servo amplifiers. You can also check it with our website for free.
http://www.mitsubishielectric.com/fa/
If you have any questions about the operation or programming of the equipment described in this guide, contact your local sales office.
In addition, when you mount a protective device, specific technical skills which are not detailed in the guide will be required.
Servo amplifiers and drive units are written as servo amplifiers in this guide under certain circumstances, unless otherwise stated.

1.2 Purpose of this guide

This installation guide explains the safe operation of MR-J4 servo amplifiers for engineers of machinery manufacturers and machine operators. For detailed information of the products, refer to "MR-D30 Instruction Manual". This installation guide does not explain how to operate equipment in which MR-D30 and MR-J4 servo amplifier are integrated.

1.3 Terms related to safety

(1) STO (Safe torque off)
Shuts off servo motor drive energy electronically based on an input signal from an external device (secondary-side output shut-off). This corresponds to stop category 0 of IEC/EN 60204-1.

(2) SS1 (Safe stop 1)
Starts deceleration based on an input signal from an external device (EM2). After a specified time for the check of stop, STO function will be activated (SS1). This corresponds to stop category 1 of IEC/EN 60204-1.

(3) SS2 (Safe stop 2)
Starts deceleration based on an input signal from an external device (EM2). After a specified time for the check of stop, the SOS function will be activated (SS2). This corresponds to stop category 2 of IEC/EN 60204-1.

(4) SOS (Safe operating stop)
This is a function to monitor whether the servo motor stops within the prescribed range for the stop position. The power is supplied to the servo motor.

(5) SLS (Safely-limited speed)
This is a function to observe whether the speed is within a regulated speed limit value. When the speed is over a specified speed, energy will be shut off by STO.

(6) SSM (Safe speed monitor)
Outputs a safety output signal when the servo motor speed is within a regulated speed.

(7) SBC (Safe brake control)
Outputs a safety output signal for an external brake control.

(8) Status monitor (SM)
Outputs a signal for the safety observation function status. This function is not the one defined in IEC/EN 61800-5-2. The function is an original function of the functional safety unit.

2. About safety

This chapter explains safety of users and machine operators. Please read the chapter carefully before mounting the equipment. In this installation guide, the specific warnings and cautions levels are classified as follows.

⚠WARNING	Indicates that incorrect handling may cause hazardous conditions, resulting in death or severe injury.
⚠CAUTION	Indicates that incorrect handling may cause hazardous conditions, resulting in medium or slight injury to personnel or may cause physical damage.

2.1 Professional engineer

Only professional engineers should mount this to MR-J4 servo amplifiers.
Here, professional engineers should meet all the conditions below.

(1) Persons who took a proper training of related work of electrical equipment or persons who can avoid risk based on past experience.

(2) Persons who have read and familiarized himself/herself with this installation guide and operating manuals for the protective devices (e.g. light curtain) connected to the safety control system.

2.2 Applications of the devices

MR-D30 has a control system whose configuration is possible to be for safety.
This product complies with the following standards.
- EN ISO 13849-1:2015 Category 3 PL d and Category 4 PL e
- IEC 61508 SIL 2 and SIL 3
- EN IEC 62061:2021 maximum SIL 2 and maximum SIL 3
- EN 61800-5-2
- IEC/EN 61800-3/GB 12668.3/KN 61800-3 (KS C 9800-3)

An achieved safety level depends on external circuit, wiring conditions, parameter settings, sensor selections, and mounting position on the machine.
A photoelectric and contact sensor such as light curtain, laser scanner, safety switch, sensor, and push button for emergency stop can be used with programs. The power of an actuator mounted on the machine or system can be shut off safely using switching output of the safety control system.

2.3 Correct use

⚠WARNING	●If you need to get close to the moving parts of the machine for inspection or others, ensure safety by confirming the power off, etc. Otherwise, it may cause an accident.

⚠CAUTION	●MR-D30 complies with basic specifications concerning radiation electromagnetic immunity and fulfills requirements of industrial uses. Therefore, MR-D30 is only for use in industrial environment, not for general use.

Use the MR-D30 within specifications. Refer to "MR-D30 Instruction Manual" for specifications such as voltage, temperature, etc. Mitsubishi Electric Co. accepts no claims for liability if the equipment is used in any other way or if modifications are made to the device, even in the context of mounting and installation.

2.3.1 Peripheral device

The following are selected based on IEC/EN 61800-5-1, UL 61800-5-1, UL 508C, and CSA C22.2 No. 274.

(1) Motor overload and Over temperature protection
The overload protection of the servo motor does not include a thermal memory function, and is not speed sensitive. The servo amplifier cannot detect overheating of the servo motor. The servo motors are protected by the servo motor overheat protection function of the servo amplifiers (a protection characteristic based on 120 % of the rated current). To provide the servo motor with overheat protection, use a magnetic contactor (electromagnetic switch) with a thermal relay. Alternatively, install a thermal sensor or equivalent equipment near the rating plate of the servo motor to check that the servo motor temperature is under 105 °C with sensing device. (Refer to Chapter 4)

2.3.2 Europe/UK compliance

The CE/UKCA marking proves the compliance of the servo product with the essential requirements specified in the relevant EU Directives and UK Regulations, and this marking also applies to machines and equipment incorporating servos.

(1) EMC requirement
The combination of MR-J4 servo amplifier and MR-D30 complies with EN/BS EN IEC 61800-3. As for I/O wires (max. length 10 m) and encoder cables (max. length 50 m), use shielded wires and ground the shields.
Install an EMC filter and surge protector on the primary side. The following shows recommended products.
EMC filter: Soshin Electric HF3000A-UN series
Surge protector: Okaya Electric Industries RSPD-250-U4 series
MR-J4 Series are not intended to be used on a low-voltage network which supplies domestic premises; electromagnetic interference is expected if used on such a network.
The installer shall provide a guide for Installation and use, including recommended mitigation devices. To avoid the risk of crosstalk to signal cables, the installation instructions shall either recommend that the power interface cable be segregated from signal cables.

(2) For Declaration of Conformity (DoC)
We declare that the servo amplifier with MR-D30 is in compliance with EC directives (Machinery directive (2006/42/EC), EMC directive (2014/30/EU), Low-voltage directive (2014/35/EU), and RoHS directive (2011/65/EU, (EU) 2015/863)) and applicable regulations of the UK. For the copy of Declaration of Conformity, contact your local sales office.

2.3.3 USA/Canada compliance

The servo amplifiers on which MR-D30 is mounted are designed in compliance with UL 508C or UL 61800-5-1 for the use in the United States. For the use in Canada, the servo amplifiers on which MR-D30 is mounted are designed in compliance with CSA C22.2 No. 274.

(1) Installation
The minimum cabinet size is 150 % of each MR-J4 servo amplifier's volume including MR-D30. Also, design the cabinet so that the ambient temperature in the cabinet is 55 °C or less. The servo amplifiers on which MR-D30 is mounted must be installed in a metal cabinet. For environment, the units should be used in open type (UL 50) and overvoltage category III or lower. MR-D30 and servo amplifier needs to be installed at or below pollution degree 2. For connection, use only copper wires.

(2) Short-circuit current rating (SCCR)
Each servo amplifier on which MR-D30 is mounted has checked with a short-circuit test.

(3) Capacitor discharge
It takes 15 minutes for capacitor discharging of the servo amplifier on which MR-D30 is mounted. Do not touch the unit and terminals immediately after power off.

(4) Branch circuit protection
For installation in United States, branch circuit protection must be provided, in accordance with the National Electrical Code and any applicable local codes. For installation in Canada, branch circuit protection must be provided, in accordance with the Canadian Electrical Code and any applicable provincial codes.

2.3.4 South Korea compliance

Products that bear the KC mark comply with the Radio Wave Law. Please note the following to use the product.
이 기기는 업무용 (A급) 전자파적합기기로서 판매자 또는 사용자는 이 점을 주의하시기 바라며, 가정외의지역에서 사용하는 것을 목적으로 합니다.
(The product is for business use (Class A) and meets the electromagnetic compatibility requirements. The seller and the user must note the above point, and use the product in a place except for home.)

2.4 Safety observation function compatible unit

The safety observation function is executed by writing a parameter to MR-D30 in a system using an MR-J4 servo amplifier, motion CPU and safety programmable controller in the following table. Set the parameters of MR-D30 correctly for a proper operation of the safety observation function. Protective functions such as the safety observation function may not work due to an incorrect setting. Refer to "MR-D30 Instruction Manual" for the parameter setting details.

(1) List of safety observation function compatible unit

Product name	Model
Servo amplifier	MR-J4-_GF-RJ/MR-J4-_GF4-RJ MR-J4-_B-RJ/MR-J4-_B4-RJ/MR-J4-_B1-RJ/MR-J4-DU_B-RJ/MR-J4-DU_B4-RJ MR-J4-_A-RJ/MR-J4-_A4-RJ/MR-J4-_A1-RJ/MR-J4-DU_A-RJ/MR-J4-DU_A4-RJ
Programmable controller (Note 1)	R_SFCPU
Motion CPU module (Note 2)	Q173DSCPU/Q172DSCPU

Note 1. For using the safety observation function through CC-Link IE Field
2. For using the safety observation function through SSCNET III/H

(2) List of safety observation function compatible unit version
(a) Servo amplifier and functional safety unit
1) MR-J4-_GF_-RJ
a) Safety observation function control by input device

MR-D30 software version	Servo amplifier software version	Safety observation function	Servo motor with functional safety	Servo amplifier
A1 or later	A3 or later (Note)	STO/SS1/SBC/SLS/SSM/SOS/SS2/SM	HG-KR_W0C HG-SR_W0C HG-JR_W0C	MR-J4-_GF_-RJ

Note. CC-Link IE Field Network Basic communication is not supported. While CC-Link IE Field Network Basic has been set, connecting with the MR-D30 functional safety unit triggers [AL. 3E.8].

b) Safety observation function control by network

MR-D30 software version	Servo amplifier software version	Safety observation function	Servo motor with functional safety	Servo amplifier
A2 or later	A3 or later	STO/SS1/SBC/SLS/SSM/SOS/SS2/SM	HG-KR_W0C HG-SR_W0C HG-JR_W0C	MR-J4-_GF_-RJ

2) MR-J4-(DU)B_-RJ/MR-J4-(DU)A_-RJ

MR-D30 software version	Servo amplifier software version	Safety observation function	Servo motor with functional safety	Servo amplifier
A0	B3 or later	STO/SS1/SBC/SLS/SSM/SM	Not compatible	MR-J4-_B_-RJ
A1 or later	B3/B4	STO/SS1/SBC/SLS/SSM/SM	Not compatible	MR-J4-_B_-RJ
	B5 or later	STO/SS1/SBC/SLS/SSM/SOS/SS2/SM	HG-KR_W0C HG-SR_W0C HG-JR_W0C	MR-J4-_B_-RJ MR-J4-_A_-RJ (Note) MR-J4-DU_B_-RJ MR-J4-DU_A_-RJ (Note)

Note. The servo amplifiers manufactured in November, 2014 or later is supported.

(b) Programmable controller

Model	Software version
R_SFCPU	07 or later

(c) Motion controller

Model	OS	Software version
Q173DSCPU	SW8DNC-SV22QJ/SW8DNC-SV13QJ	05 or later
Q172DSCPU	SW8DNC-SV22QL/SW8DNC-SV13QL	

2.5 General cautions for safety protection and protective measures

POINT
●Observe the cautions for safety protection and protective measures.
●Observe the items in this section for proper use of MR-D30.

(1) When mounting, installing, and using the MR-D30, always observe standards and directives applicable in the country.

(2) When using an MR-D30 in an EU member state, comply with the following directives.
- Machinery directive 2006/42/EC
- EMC directive 2014/30/EU
- Low voltage directive 2014/35/EU
- RoHS directive 2011/65/EU
- Other laws/regulations of labor safety

(3) The manufacturer and owner of machines on which an MR-D30 is used should be familiarized with all the applicable laws and regulations and should be responsible to observe them.
For Declaration of Conformity (DoC), our company declares that the servo amplifiers are in compliance with the necessary requirements and standards (2006/42/EC, 2014/30/EU, 2014/35/EU and 2011/65/EU). You can obtain the copy of Declaration of Conformity from our website.

(4) The contents of "MR-D30 Instruction Manual" must be observed.

(5) Tests should be performed by professional engineers, especially qualified and responsible personnel, and should be recorded/documented for a third party to rebuild and confirm the tests.

(6) Based on IEC/EN 60204-1, connect to a power supply that has tolerance against instantaneous power failure of 20 ms or more.

2.6 Disposal

Disposal of unusable or irreparable devices should always occur in accordance with the applicable country-specific waste disposal regulations.

2.7 Risk assessment

To ensure safety, users should decide all the risk assessments and residual risks in the entire machine equipment. A company and/or individual who constructed the safety related system must take full responsibility for installation and commissioning of the system. Additionally, when complying with a European machinery directive, the system must acquire safety standards certification as a whole.
Perform all risk assessments and safe level certification to the machine or the system as a whole. It is recommended that a Certification Body final safety certification of the system be used.
The following shows residual risks concerning the safety observation function of this product.

2.7.1 Common residual risks in each function

(1) At the shipment to end-users, check the settings of safety related components with programming tools and monitored/displayed contents on display and record and save the setting data concerning the safety observation function and the programming tools you used. Perform them using a check sheet, etc.

(2) The safety will not be ensured such as in assembling machine until installing, wiring, and adjustment are completed properly. Install, wire, and adjust your system referring to installation guide for each unit.

(3) Only qualified personnel are authorized to install, start-up, repair or adjust the machines in which these components are installed. Only trained engineers should install and operate the equipment. (ISO 13849-1:2015 Table F.1 No. 5)

(4) Separate the wiring for safety observation function from other signal wirings. (ISO 13849-1:2015 Table F.1 No. 1)

(5) Protect the cables with appropriate ways (routing them in a cabinet, using a cable guard, etc.).

(6) We recommend using a switch, relay, sensor, etc. which comply with safety standards. When using a switch, relay, sensor, etc. which do not comply with safety standards, perform a safety confirmation.

(7) Keep the required clearance/creepage distance depending on voltage you use.

(8) The time to a safety observation error depends on parameter settings.

2.7.2 Residual risks in each function

(1) Speed monitoring (SLS)
(a) Speed monitoring function guarantees the servo motor speed), but it does not guarantee the actual machine safety speed. Set parameters so that the safe speed of the machine is the same as the safety speed of the specified motor.
(b) Check if the speed of the monitored servo axis is the same as the actual speed by using a tachometer, etc. considering the speed includes an error caused by the command and encoder resolution.
(c) The defect of the mechanical section such as slid of shaft and wanting of a timing belt, etc. is not covered. Be sure to eliminate the risk of mechanical section before operation.
(d) Speed monitoring error detection time is set to 1 ms. Error in shorter than this time are not detected.
(e) After speed is over the limit, safety observation error (shut-off signal off) does not occur during the speed error detection time set by the parameter. Make sure that safety can be ensured during this period.

(2) Safe speed monitor (SSM)
When SSM is used as a restart trigger, perform it according to IEC/EN 60204-1.

(3) Safe brake control (SBC)
This function guarantees only that power to mechanic break is properly supplied and abrasion of the brake cannot be detected. Check this function regularly that the mechanic brake can operate.

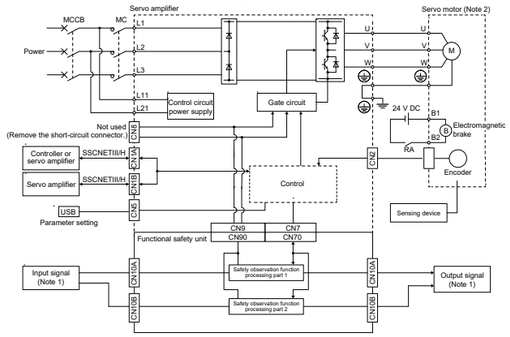
3. Conditions of use for the product

(1) MR-D30 complies with a safety standard, but this fact does not guarantee that MR-D30 will be free from any malfunction or failure. The user of this product shall comply with any and all applicable safety standard, regulation or law and take appropriate safety measures for the system in which the product is installed or used and shall take the second or third safety measures other than the product. Our company is not liable for damages that could have been prevented by compliance with any applicable safety standard, regulation or law.

(2) Our company prohibits the use of Products with or in any application involving, and we shall not be liable for a default, a liability for defect warranty, a quality assurance, negligence or other tort and a product liability in these applications.
(a) Power plants
(b) Trains, railway systems, airplanes, airline operations, and other transportation systems
(c) Hospitals, medical care, dialysis and life support facilities or equipment
(d) Amusement equipment
(e) Incineration and fuel devices
(f) Handling of nuclear or hazardous materials or chemicals
(g) Mining and drilling
(h) Other applications where the level of risk to human life, health or property are elevated.

4. Block diagram and timing chart

(1) Function block diagram (for using input signal)
This is an example of a combination with MR-J4-_B_-RJ.



Note 1. Safety switch, safety relay, etc.
2. The servo motor with functional safety is required to use the SS2/SOS functions.

(2) How to use the functions
To use the safety observation functions, combine MR-D30 with MR-J4. For how to use the functions, refer to "MR-D30 Instruction Manual".

5. Maintenance and disposal

MR-D30 safety logic unit is equipped with LED displays to check errors for maintenance.
Please dispose this unit according to your local laws and regulations.
Changing the combination of MR-D30 and MR-J4 servo amplifier will trigger [AL. 7A.4 Functional safety unit combination error (safety observation function)] and the safety observation function you set will not operate.

6. Functions and configuration

6.1 Summary

(1) Safety observation functions are available with your servo amplifier.
Mounting the functional safety unit to the servo amplifier enables you to use the safety observation functions such as STO/SS1/SS2/SOS/SLS/SSM/SBC without depending on a controller.

(2) Drive safety compatible integrated motion controller
Safety communication with motion controllers is available by using MR-D30 with MR-J4-_B_-RJ. With this, the wiring which was required can be reduced for the STO signal and encoder signal for safety observation.

(3) Drive safety integrated programmable controller
Safety communication with safety programmable controller is available by using MR-D30 with MR-J4-_GF_-RJ. With this, the wiring which was required can be reduced for the STO signal and encoder signal for safety observation.

6.2 Transportation and storage

⚠CAUTION	●Transport the products correctly according to their mass. ●Stacking in excess of the limited number of product packages is not allowed. ●Install the equipment in a load-bearing place in accordance with "MR-D30 Instruction Manual". ●Do not put excessive load on the machine.

When you keep or use it, please fulfill the following environment.

Item		Environment
Ambient temperature	Operation [°C]	0 to 55 Class 3K3 (IEC/EN 60721-3-3)
	Transportation (Note) [°C]	-20 to 65 Class 2K12 (IEC/EN 60721-3-2)
	Storage (Note) [°C]	-20 to 65 Class 1K4 (IEC/EN 60721-3-1)
Ambient humidity	Operation, transportation, storage	5 %RH to 90 %RH
Vibration resistance	Test condition	10 Hz to 57 Hz with amplitude of 0.075 mm 57 Hz to 150 Hz with constant acceleration of 9.8 m/s² to IEC/EN 61800-5-1 (Test Fc of IEC 60068-2-6)
	Operation	5.9 m/s² (X, Y, Z axes)
	Transportation (Note)	Class 2M3 (IEC/EN 60721-3-2)
	Storage	Class 1M2 (IEC/EN 60721-3-2)
Pollution degree		2
IP rating		Mounted on a servo amplifier: IP20 (IEC/EN 60529) MR-D30 (single): IP00 (IEC/EN 60529)
		Open type (UL 50)
Altitude	Operation, storage	2000 m or less
	Transportation	10000 m or less

Note. In regular transport packaging

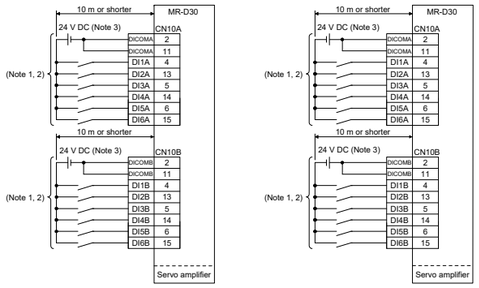
6.3 Specifications

Model		MR-D30
Output	Rated voltage	24 V DC
	Rated current [A]	0.3
Interface power supply	Voltage	24 V DC ± 10 %
	Power supply capacity [A]	0.8 (Note 1)
Safety performance	Standards certified by CB	EN ISO 13849-1:2015 Category 4, PL e and Category 3, PL d IEC 61508 SIL 2 and SIL 3 EN IEC 62061:2021 maximum SIL 2 and maximum SIL 3 EN 61800-5-2
	Mean time to dangerous failure (MTTFd)	MTTFd ≥ 100 [years] (313a)
	Diagnostic coverage (DC)	DC = High, 97.6 [%]
	Probability of dangerous failures per hour (PFH)	PFH = 6.57 × 10^{-9} [1/h]
	Mission time (T_M)	T_M = 20 [years]
	Response performance (Note 2)	Using input device: 15 ms or less Using a drive Safety integrated motion controller: 60 ms or less Using drive safety integrated programmable controller: 65 ms or less
	Speed observation resolution	Depends on a command resolution (22 bit position command: 0.1 r/min or less)
	Position observation resolution	1/32 rev
	Safety position data resolution	32 pulses/rev (5 bits)
	Input device	6 points × 2 systems (source/sink)
	Output device	Source: 3 points × 2 systems and 1 point × 1 system Sink: 1 point × 1 system
Safety observation function (IEC/EN 61800-5-2)	Safe torque off (STO)	Category 4, PL e, SIL 3 (Note 3)/Category 3, PL d, SIL 2
	Safe stop 1 (SS1)	Category 4, PL e, SIL 3 (Note 3)/Category 3, PL d, SIL 2
	Safely-limited speed (SLS) (Note 7)	Category 4, PL e, SIL 3 (Note 3, 4)/Category 3, PL d, SIL 2
	Safe speed monitor (SSM) (Note 7)	Category 4, PL e, SIL 3 (Note 3, 4)/Category 3, PL d, SIL 2
	Safe brake control (SBC)	Category 4, PL e, SIL 3 (Note 3)/Category 3, PL d, SIL 2
	Safe operating stop (SOS) (Note 5, 7)	Category 4, PL e, SIL 3 (Note 3)/Category 3, PL d, SIL 2
	Safe stop 2 (SS2) (Note 5, 7)	Category 4, PL e, SIL 3 (Note 3)/Category 3, PL d, SIL 2
Safety observation function	Status monitor (STO/SOS)	Category 4, PL e, SIL 3/Category 3, PL d, SIL 2 (Note 6)
Compliance to global standards	CE marking	EMC: EN 61800-3 MD: EN ISO 13849-1:2015, EN 61800-5-2, EN IEC 62061:2021
Structure (IP rating)		Natural cooling, open (mounted on a servo amplifier: IP20, MR-D30 (single): IP00)
Mass [g]		150

Note 1. This is the value applicable when all I/O signals are used. The current capacity can be decreased by reducing the number of I/O points.
2. Time from STO input off to energy shut off
3. To meet Category 4, PL e, SIL 3 for input signals, a diagnosis using test pulses is required.
4. To meet Category 4, PL e, SIL 3, using with a servo motor with functional safety is required.
5. To enable SS2 and SOS, using with a servo motor with functional safety is required.
6. For the achievable safety level, refer to the section of "Safety observation function (IEC/EN 61800-5-2)".
7. The scale measurement function of the semi closed loop system, linear servo system, direct drive servo system, and fully closed loop system are not compatible with SLS, SSM, SS2, and SOS. The MR-J4-_GF_-RJ with software version B0 or later used in a direct drive servo system is compatible with SLS and SSM.

6.4 When using MR-D30 for an MR-J4 series servo amplifier

6.4.1 Input signal



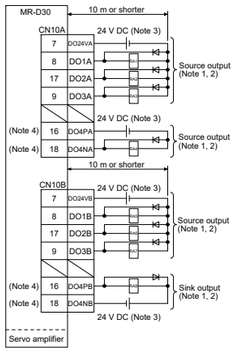
Note 1. Separate all the external wires by two types, CN10A and CN10B.
2. Assign each input device to the following combinations of connector and pin. Refer to chapter 7 for each device.

Combination of connector and pin for input
DI1A (CN10A-4)/DI1B (CN10B-4)
DI2A (CN10A-13)/DI2B (CN10B-13)
DI3A (CN10A-5)/DI3B (CN10B-5)
DI4A (CN10A-14)/DI4B (CN10B-14)
DI5A (CN10A-6)/DI5B (CN10B-6)
DI6A (CN10A-15)/DI6B (CN10B-15)

3. Supply 24 V DC ± 10 % to interfaces from outside. When all the I/O points are used, the required current capacity is 0.8 A in total. The current capacity can be decreased by reducing the number of I/O points. Refer to section 7.2 that gives the current value necessary for the interface. The illustration of the 24 V DC power supply is divided between input signal and output signal for convenience. However, they can be configured by one.

6.4.2 Output signal

DO1A to DO3A, DO1B to DO3B, and DO4NA can be used as source outputs, and DO4PB can be used as a sink output.



Note 1. Separate all the external wires by two types, CN10A and CN10B. Be sure to wire them separately by the two types for power supply for I/O (24 V DC, 0 V common). Do not mix them when wiring.
2. Assign each output device to the following combinations of connector and pin. Refer to chapter 7 for each device.

Combination of connector and pin for output
DO1A (CN10A-8)/DO1B (CN10B-8)
DO2A (CN10A-17)/DO2B (CN10B-17)
DO3A (CN10A-9)/DO3B (CN10B-9)
DO4NA (CN10A-18)/DO4PB (CN10B-16)

3. Supply 24 V DC ± 10 % to interfaces from outside. When all the I/O points are used, the required current capacity is 0.8 A in total. The current capacity can be decreased by reducing the number of I/O points. Refer to section 7.2 that gives the current value necessary for the interface. The illustration of the 24 V DC power supply is divided between input signal and output signal for convenience. However, they can be configured by one.
4. DO4PA (CN10A-16), DO4NA (CN10A-18), DO4PB (CN10B-16) and DO4NB (CN10B-18) will not be available with MR-D30 manufactured in September 2014 or before. Do not connect anything to these pins.

7. Signals

7.1 Connector and pin assignment

(1) Input device

Assign the devices to DI1_ to DI6_ with [Pr. PSD02 Input device selection DI1] to [Pr. PSD07 Input device selection DI6]. For the safety observation function control by network, you can input through network.

Device	Symbol	Connector and pin No.	Function	Input pin status which the function turns to be enabled
STO command	STOC	CN10A-4 CN10A-5 CN10A-6 CN10A-13 CN10A-14 CN10A-15 CN10B-4 CN10B-5 CN10B-6 CN10B-13 CN10B-14 CN10B-15	The STO function operates by the STO command.	Opened
SS1 command	SS1C		The SS1 function operates by the SS1 command.	Opened
SS2 command	SS2C		The SS2/SOS functions operate by the SS2/SOS command.	Opened
SLS1 command	SLS1C		The SLS function 1 operates by the SLS1 command. [Pr. PSA07 SLS deceleration monitoring time 1] and [Pr. PSA11 SLS speed 1] are used as parameters.	Opened
SLS2 command	SLS2C		The SLS function 2 operates by the SLS2 command. [Pr. PSA08 SLS deceleration monitoring time 2] and [Pr. PSA12 SLS speed 2] are used as parameters.	Opened
SLS3 command	SLS3C		The SLS function 3 operates by the SLS3 command. [Pr. PSA09 SLS deceleration monitoring time 3] and [Pr. PSA13 SLS speed 3] are used as parameters.	Opened
SLS4 command	SLS4C		The SLS function 4 operates by the SLS4 command. [Pr. PSA10 SLS deceleration monitoring time 4] and [Pr. PSA14 SLS speed 4] are used as parameters.	Opened
Test pulse output A	PLSA	CN10A-12	Outputs test pulses for external wiring diagnosis.	
Test pulse output B	PLSB	CN10B-12	Outputs test pulses for external wiring diagnosis.	

(2) Output device

The status monitor (SM) of the safety observation function is output from DO1_ to DO4_. The devices can be assigned to DO1_ to DO4_ with [Pr. PSD08 Output device selection DO1] to [Pr. PSD11 Output device selection DO3]. For the safety observation function control by network, you can output through network. Then, DO1_ to DO4_ can be used simultaneously.

Device	Symbol	Connector and pin No.	Function	Output pin status during operation
SSM output	SSMS	CN10A-8 CN10A-9 CN10A-17 CN10A-18 CN10B-8 CN10B-9 CN10B-17 CN10B-16	Indicates that the servo motor speed is at SLS speed or less while speed observation is operating by SLS function.	Closed
SBC output	SBCS		Outputs a control signal of the electromagnetic brake.	Opened
STO output	STOS		This is a monitor output signal meaning that the STO function is operating.	Opened
SOS output	SOSS		This is a monitor output signal meaning that the SS2/SOS function is operating.	Opened
SS1 output	SS1S		This is a monitor output signal meaning that the SS1 function is operating.	Opened
SS2 output	SS2S		This is a monitor output signal meaning that the SS2/SOS function monitors the servo motor is in the stop state.	Opened
SLS1 output	SLS1S		This is a monitor output signal meaning that the SLS function 1 is operating.	Opened
SLS2 output	SLS2S		This is a monitor output signal meaning that the SLS function 2 is operating.	Opened
SLS3 output	SLS3S		This is a monitor output signal meaning that the SLS function 3 is operating.	Opened
SLS4 output	SLS4S		This is a monitor output signal meaning that the SLS function 4 is operating.	Opened

(3) Power supply

Name	Symbol	Connector and pin No.	Function and application
Digital input I/F common A	DICOMA	CN10A-2 CN10A-11	This is a common terminal for input signal. Input 24 V DC (24 V DC ± 10 % 0.8 A) for I/O interface. The power supply capacity changes depending on the number of I/O interface points to be used. For sink interface, connect + of 24 V DC external power supply. For source interface, connect - of 24 V DC external power supply.
Test pulse power supply input A	DC24VA	CN10A-1 CN10A-10	Input a power supply to output test pulses for external wiring diagnosis. Connect the positive terminal of the 24 V DC external power supply.
Digital output I/F common A	DO24VA	CN10A-7	This is a common terminal for output signal. For source interface, connect + of 24 V DC external power supply.
DO4A power supply for digital output I/F	DO4PA	CN10A-16	This is the power terminal for the DO4A output signal. Connect the positive terminal of the 24 V DC external power supply.
Digital input I/F common B	DICOMB	CN10B-2 CN10B-11	This is a common terminal for input signal. Input 24 V DC (24 V DC ± 10 % 0.8 A) for I/O interface. The power supply capacity changes depending on the number of I/O interface points to be used. For sink interface, connect + of 24 V DC external power supply. For source interface, connect - of 24 V DC external power supply.
Test pulse power supply input B	DC24VB	CN10B-1 CN10B-10	Input a power supply to output test pulses for external wiring diagnosis. Connect the positive terminal of the 24 V DC external power supply.
Digital output I/F common B	DO24VB	CN10B-7	This is a common terminal for output signal. For source interface, connect + of 24 V DC external power supply.
DO4B power supply for digital output I/F	DO4NB	CN10B-18	This is the power terminal for the DO4B output signal. Connect the negative terminal of the 24 V DC external power supply.

7.2 Interface (source I/O)

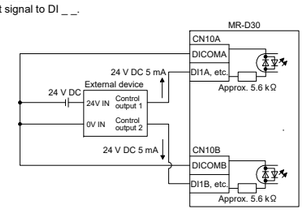
For MR-D30, source type I/O interfaces can be used. The following shows an example of source interface.

(1) Input interface

For MR-D30, source type and sink type I/O interfaces can be used. Transmit signals from source (open-collector) type transistor output, relay switch, etc. For sink interface, refer to "MR-D30 Instruction Manual".

(a) External device connection

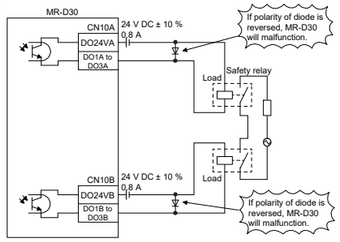
Connect the output signal to DI _ _.



(2) Output interface

When the output transistor is turned on, the current flows from the output terminal to a load. A lamp, relay or photocoupler can be driven. Install a diode (D) for an inductive load, or install an inrush current suppressing resistor (R) for a lamp load. (Rated current: 5 mA to 40 mA, maximum current: 50 mA, inrush current: 100 mA or less)

A 2.4 V voltage drop occurs in MR-D30.



7.3 Wiring method of CN10A and CN10B connectors

Handle with the tool with care when connecting wires.

(1) Wire strip

(a) Use wires with size of AWG 24 to 16 (recommended electric wire: UL 1007) and strip the wires to make the stripped length 10 mm ± 0.5 mm. Confirm the stripped length with gauge, etc. before using the wires.

(b) If the stripped wires are bent, loose or too thick due to twisting too much, fix the wires by twisting lightly, etc. Then, confirm the stripped length before using the wires. Do not use excessively deformed wires.

(c) Smooth out the wire surface and stripped insulator surface.

(2) Connecting wires

Before connecting wires, be sure to pull out the receptacle assembly from the header connector. If wires are connected with inserted connector, the connector and the printed board may malfunction.

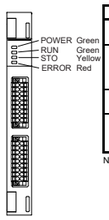
With pressing the release button with a flat-blade screwdriver with the blade edge width of 2.0 mm to 2.5 mm, insert a wire all the way in and remove the screwdriver. Refer to "MR-D30 Instruction Manual" for wiring.

(3) Connectors

Be sure to insert the connector all the way straight until you hear or feel clicking. After connection, tighten the screw came with the connector using a flat-blade screwdriver. Loosen the screw before disconnection.

8. Display

MR-D30 has four LED indications. They indicate the followings.



LED	Lighting status	Description
POWER	Lit	Power is being supplied.
	Extinguished	Power is not supplied.
RUN	Lit	The safety observation function is performing. STO, SS1, SS2/SOS, or SLS function is being executed normally, performing shutoff or observation.
	Extinguished	The safety observation function is not performing. Because the operation commands are not inputted or an internal diagnosis error has occurred.
STO	Lit	STO function is performing. The power to the motors is shut off.
	Extinguished	STO function is not performing. The power to the motors is not shut off.
ERROR	Lit	Some errors have been detected for MR-D30. (Note)
	Blinking	Some errors have been detected for MR-D30.
	Extinguished	An error is not being detected in MR-D30.

Note. When a servo amplifier which is not compatible with MR-D30 is connected to MR-D30, "ERROR" will light. Check if MR-D30 is connected to the MR-J4-_B_-RJ servo amplifier with the software version B3 or later, or the MR-J4-_A_-RJ servo amplifier with the software version B5 or later. (Refer to (3) (a) of section 2.3.4.)

The following shows indication example of each state.

POWER	RUN	STO	ERROR	Servo amplifier display	Status	Description
●	●	●	●	Normal	Power off	Power is not supplied.
○	●	○	●	95._ or Ab	During diagnosis	For the safety observation function control by input device, execute a fixing-diagnosis at start-up. For the safety observation function control by network, connect networks.
○	●	●	●	Normal	Safety observation function is not performing.	The safety observation function is not performing.
○	○	○	●	95._	Safety observation function is performing (shutting power off).	STO or SS1 function is performing.
○	○	●	●	Normal	Safety observation function is performing (monitoring).	SLS or SS2/SOS function is performing.
○	●/○	○	◎/○	Alarm No.	Error has occurred.	An error has been detected. Refer to chapter 8 for error details. (Note)
○	○	○	○	Alarm No.	Error has occurred (watchdog)	Watchdog is occurring due to parts error, such as the CPU.

(○: Lit, ◎: Blinks, ●: Extinguished)

Note. When a servo amplifier which is not compatible with MR-D30 is connected to MR-D30, "ERROR" will light. Refer to section 2.3.4 (3) (a) for the software version of a servo amplifier that is compatible with MR-D30.

9. Setting method

Use MR Configurator2 for the settings. Refer to "MR-D30 Instruction Manual" for details.

Check the contents of [Pr. PSA _ _], [Pr. PSC _ _], and [Pr. PSD _ _] and set [Pr. PSA01 Safety observation function activation setting] to "_ _ _ 1". Until setting this parameter, STO cannot be canceled due to [AL. 7A Parameter setting error (safety observation function)] occurrence.

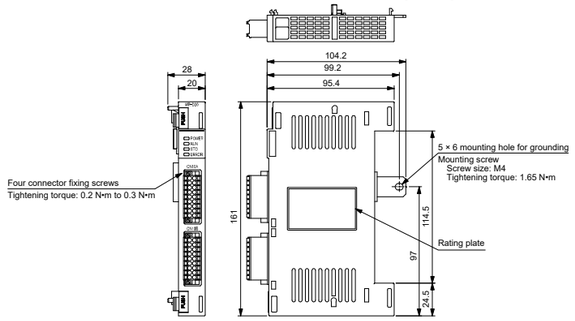
10. Troubleshooting

When power is not supplied or ERROR LED turns on, refer the following table and take the appropriate action.

Event	Description	Cause	Action
Power is not supplied.	Power LED does not turn on although power is supplied.	1. The servo amplifier is malfunctioning.	Replace the servo amplifier.
		2. MR-D30 is not connected to the servo amplifier properly.	Check the connection.
		3. MR-D30 is malfunctioning.	Replace the MR-D30.
ERROR LED is blinking.	ERROR LED is blinking and an alarm No. is displayed on the servo amplifier.	An error has occurred in MR-D30 or servo amplifier.	Check the alarm No. and remove the problem referring to "MELSERVO-J4 Servo Amplifier Instruction Manual (Troubleshooting)".
ERROR LED is on.	ERROR LED has been on.	MR-D30 is malfunctioning.	Replace the MR-D30.

11. Dimensions

[Unit: mm]



Mass: 0.15 [kg]

CN10A

No.	Symbol	Symbol	No.
10	DC24VA	DC24VA	1
11	DICOMA	DICOMA	2
12	PLSA		3
13	DI2A	DI1A	4
14	DI4A	DI3A	5
15	DI6A	DI5A	6
16	DO4PA	DO24VA	7
17	DO2A	DO1A	8
18	DO4NA	DO3A	9

CN10B

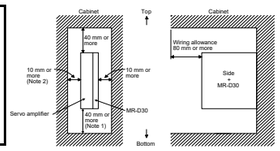
No.	Symbol	Symbol	No.
10	DC24VB	DC24VB	1
11	DICOMB	DICOMB	2
12	PLSB		3
13	DI2B	DI1B	4
14	DI4B	DI3B	5
15	DI6B	DI5B	6
16	DO4PB	DO24VB	7
17	DO2B	DO1B	8
18	DO4NB	DO3B	9

12. Installation

Installation direction and clearances

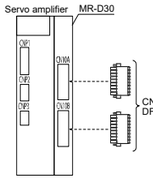
⚠CAUTION

- The devices must be installed in the specified direction. Not doing so may cause a malfunction.
- Mount the servo amplifier on a cabinet which meets IP54 in the correct vertical direction to maintain pollution degree 2.
- Even if the power turned off, touching the resistor will cause an electric shock because the capacitor of the servo amplifier is charged for a while.



Note 1. For 11 kW to 22 kW servo amplifiers, the clearance between the bottom and ground will be 120 mm or more.
2. For MR-J4-500_-RJ, the clearance on the left side will be 25 mm or more.

13 Connector



14. Check list for user documentation

MITSUBISHI ELECTRIC

MR-D30 installation checklist for manufacturer/installer

The following items must be satisfied by the initial test operation at least. The manufacturer/installer must be responsible for checking the standards in the items.

Maintain and keep this checklist with related documents of machines to use this for periodic inspection.

1. Is it based on directive/standard applied to the machine? Yes [ ], No [ ]
2. Is directive/standard contained in Declaration of Conformity (DoC)? Yes [ ], No [ ]
3. Does the protection instrument conform to the category required? Yes [ ], No [ ]
4. Are electric shock protective measures (protective class) effective? Yes [ ], No [ ]
5. Is the safety observation function checked (test of all the shut-off wiring)? Yes [ ], No [ ]

Checking the items will not be instead of the first test operation or periodic inspection by professional engineers.

Warranty

1. Warranty period and coverage

We will repair any failure or defect hereinafter referred to as "failure" in our FA equipment hereinafter referred to as the "Product" arisen during warranty period at no charge due to causes for which we are responsible through the distributor from which you purchased the Product or our service provider. However, we will charge the actual cost of dispatching our engineer for an on-site repair work on request by customer in Japan or overseas countries. We are not responsible for any on-site readjustment and/or trial run that may be required after a defective unit are repaired or replaced.

[Term]

For terms of warranty, please contact your original place of purchase.

[Limitations]

(1) You are requested to conduct an initial failure diagnosis by yourself, as a general rule.
It can also be carried out by us or our service company upon your request and the actual cost will be charged. However, it will not be charged if we are responsible for the cause of the failure.

(2) This limited warranty applies only when the condition, method, environment, etc. of use are in compliance with the terms and conditions and instructions that are set forth in the instruction manual and user manual for the Product and the caution label affixed to the Product.

(3) Even during the term of warranty, the repair cost will be charged on you in the following cases;
1. a failure caused by your improper storing or handling, carelessness or negligence, etc., and a failure caused by your hardware or software problem
2. a failure caused by any alteration, etc. to the Product made on your side without our approval
3. a failure which may be regarded as avoidable, if your equipment in which the Product is incorporated is equipped with a safety device required by applicable laws and has any function or structure considered to be indispensable according to a common sense in the industry
4. a failure which may be regarded as avoidable if consumable parts designated in the instruction manual, etc. are duly maintained and replaced
5. any replacement of consumable parts (battery, fan, smoothing capacitor, etc.)
6. a failure caused by external factors such as inevitable accidents, including without limitation fire and abnormal fluctuation of voltage, and acts of God, including without limitation earthquake, lightning and natural disasters
7. a failure generated by an unforeseeable cause with a scientific technology that was not available at the time of the shipment of the Product from our company
8. any other failures which we are not responsible for or which you acknowledge we are not responsible for

2. Term of warranty after the stop of production

(1) We may accept the repair at charge for another seven (7) years after the production of the product is discontinued. The announcement of the stop of production for each model can be seen in our Sales and Service, etc.

(2) Please note that the Product (including its spare parts) cannot be ordered after its stop of production.

3. Service in overseas countries

Our regional FA Center in overseas countries will accept the repair work of the Product. However, the terms and conditions of the repair work may differ depending on each FA Center. Please ask your local FA center for details.

4. Exclusion of loss in opportunity and secondary loss from warranty liability

Regardless of the gratis warranty term, Mitsubishi shall not be liable for compensation to:

(1) Damages caused by any cause found not to be the responsibility of Mitsubishi.

(2) Loss in opportunity, lost profits incurred to the user by Failures of Mitsubishi products.

(3) Special damages and secondary damages whether foreseeable or not, compensation for accidents, and compensation for damages to products other than Mitsubishi products.

(4) Replacement by the user, maintenance of on-site equipment, start-up test run and other tasks.

5. Change of Product specifications

Specifications listed in our catalogs, manuals or technical documents may be changed without notice.

6. Application and use of the Product

(1) For the use of our AC Servo, its applications should be those that may not result in a serious damage even if any failure or malfunction occurs in AC Servo, and a backup or fail-safe function should operate on an external system to AC Servo when any failure or malfunction occurs.

(2) Our AC Servo is designed and manufactured as a general purpose product for use at general industries.
Therefore, applications substantially influential on the public interest for such as atomic power plants and other power plants of electric power companies, and also which require a special quality assurance system, including applications for railway companies and government or public offices are not recommended, and we assume no responsibility for any failure caused by these applications when used.
In addition, applications which may be substantially influential to human lives or properties for such as airlines, medical treatments, railway service, incineration and fuel systems, man-operated material handling equipment, entertainment machines, safety machines, etc. are not recommended, and we assume no responsibility for any failure caused by these applications when used.
We will review the acceptability of the abovementioned applications, if you agree not to require a specific quality for a specific application. Please contact us for consultation.

(3) Mitsubishi Electric shall have no responsibility or liability for any problems involving programmable controller trouble and system trouble caused by DoS attacks, unauthorized access, computer viruses, and other cyberattacks.